

3	Setting-up and Running an Aircraft Model	26		
3.1	Aircraft Model Examples	27	4.2.9	Roll Moment Coefficient 60
3.2	Building an aircraft configuration	28	4.2.10	Yaw Moment Coefficient 61
3.2.1	Conventions	28	4.3	Atmosphere 62
3.2.2	Section 1: Aerodynamics	28	4.3.1	Standard Atmosphere 63
3.2.3	Section 2: Propeller	29	4.3.2	Background Wind 64
3.2.4	Section 3: Engine	30	4.3.3	Turbulence 65
3.2.5	Section 4: Inertia	31	4.3.4	Wind Shear 66
3.2.6	Section 5: Other parameters	31	4.3.5	Wind Force 67
3.3	The pre-built Aircraft Models	32	4.3.6	Wind Moment 68
3.4	Using FlightGear Aircraft Configuration Files . . .	35	4.4	Complete Aircraft 69
3.4.1	The JSBSim XML Configuration File . . .	35	4.4.1	6-DOF Aircraft Model - body-frame EOM 70
3.4.2	The xmlAircraft Parser	36	4.4.2	6-DOF Aircraft Model - geodetic-frame EOM 73
3.4.3	The Matlab Aircraft Structure	37	4.4.3	6-DOF Aircraft Model - geodetic-frame EOM, no magnetic field 76
3.5	Additional Matlab Utilities	40	4.4.4	Simple Aircraft Model 79
4	Block Reference	41	4.4.5	Glider Model 81
4.1	Actuators	42	4.4.6	Inertial Navigation System 83
4.1.1	Simple Actuator (1st-order dynamics) . . .	43	4.5	Earth 84
4.1.2	Simple Actuator (2nd-order dynamics) . .	45	4.5.1	WGS-84 85
4.1.3	D/A Converter	46	4.5.2	EGM-96 86
4.2	Aerodynamics	47	4.5.3	Ground Detection 87
4.2.1	Aerodynamic Force	48	4.5.4	WMM-2000 88
4.2.2	Aerodynamic Moment	49	4.6	Equations of Motion 89
4.2.3	Wind-axes Velocities	50	4.6.1	Total Acceleration 90
4.2.4	Dynamic Pressure	52	4.6.2	Total Moment 91
4.2.5	Lift Coefficient	53	4.6.3	Body-frame EOM: Forces 92
4.2.6	Drag Coefficient	55	4.6.4	Body-frame EOM: Moments 93
4.2.7	Side Force coefficient	57	4.6.5	Body-frame EOM: Kinematics (Quaternions) 94
4.2.8	Pitch Moment Coefficient	58	4.6.6	Body-frame EOM: Kinematics (Euler An- gles) 95

4.6.7	Body-frame EOM: Navigation	96	4.11.3	Simple Sensor - 1st-order dynamics	135
4.6.8	Geodetic-frame EOM: Position	98	4.11.4	Simple Sensor - 2nd-order dynamics	136
4.6.9	Geodetic-frame EOM: Velocity	100	4.11.5	Analog Sensor	137
4.6.10	Geodetic-frame EOM: Attitude (Quaternions)	102	4.11.6	A/D Converter	138
4.6.11	Geodetic-frame EOM: Attitude (Euler An- gles)	103	4.11.7	Single GPS Measurement	139
4.6.12	Geodetic-frame EOM: Angular Rate	104	4.11.8	GPS PV	140
4.7	Inertia	106	4.12	Transformations	141
4.7.1	Aircraft Inertia	107	4.12.1	Body-Inertial DCM From Quaternions	142
4.7.2	Inertia Coefficients	109	4.12.2	Body-Inertial DCM From Euler Angles	143
4.8	Math	110	4.12.3	Body-Wind DCM	144
4.8.1	Cross Product	111	4.12.4	Euler Angles From Quaternions	145
4.8.2	Normalization	112	4.12.5	Euler Angles from DCM	146
4.8.3	Vector Norm	113	4.12.6	Quaternions From Euler Angles	147
4.8.4	Non-zero Sign	114	4.12.7	ECEF Position	148
4.8.5	Zero Offset	115	4.13	Unit Conversion	149
4.8.6	pi Bound	116	4.13.1	Angular position: Deg 2 rad and Rad 2 deg	150
4.8.7	2pi Bound	117	4.13.2	Angular velocity: Rad/s 2 RPM and RPM 2 rad/s	151
4.9	Pilot Interface	118	4.13.3	Distance: ft 2 m and m 2 ft	152
4.9.1	FS Interface	119	4.13.4	Distance: m 2 nm and nm to m	153
4.9.2	FlightGear Interface	121	4.13.5	Velocity: m/s 2 km/h and km/h 2 m/s	154
4.9.3	Joystick Interface	123	4.13.6	Velocity: m/s 2 mph and mph 2 m/s	155
4.9.4	CH F-16 Combat Stick	124	4.13.7	Velocity: m/s 2 kts and kts 2 m/s	156
4.10	Propulsion	126	4.13.8	Force: lbf 2 N and N 2 lbf	157
4.10.1	Fixed-Pitch Propeller	127	4.13.9	Mass: lb 2 kg and kg 2 lb	158
4.10.2	Piston Engine	128	4.13.10	Mass: slug 2 kg and kg 2 slug	159
4.10.3	GA Propulsion System	130	4.13.11	Volume: gal 2 l and l 2 gal	160
4.11	Sensors	132	4.13.12	Pressure: Pa 2 in.Hg. and in.Hg. 2 Pa	161
4.11.1	Noise Correlation: Random Walk	133	4.13.13	Temperature: K 2 F and F 2 K	162
4.11.2	Noise Correlation: Gauss-Markov Process .	134	4.14	FlightGear-Compatible	163

4.14.1	Inertia: Empty Aircraft	164
4.14.2	Inertia: Point Mass	165
4.14.3	Propulsion: FG Piston Engine + Fixed- Pitch Prop	166
4.14.4	Propulsion: FG Piston Engine + Variable- Pitch Prop	168
4.14.5	Piston Engine: Intake Model	170
4.14.6	Piston Engine: AirFlow Model	171
4.14.7	Piston Engine: FuelFlow Model	172
4.14.8	Piston Engine: Power Model	173
4.14.9	Piston Engine: FG Piston Engine	174
4.14.10	Propeller Thruster: FG Fixed-Pitch Propeller	175
4.14.11	Propeller Thruster: FG Variable-Pitch Pro- peller	176
4.14.12	Tank: Fuel Tank	177
4.14.13	Aerodynamics: Value	178
4.14.14	Aerodynamics: Vector	179
4.14.15	Aerodynamics: Table	180
4.14.16	Aerodynamics: Coefficient	181
4.14.17	Complete Aircraft: Cessna-172	182
4.14.18	Complete Aircraft: Cessna-182	184
4.14.19	Complete Aircraft: Cessna-310	186